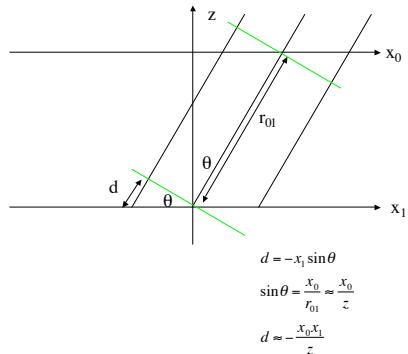


Bioengineering 280A
Principles of Biomedical Imaging

Fall Quarter 2005
Ultrasound Lecture 2

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Plane Wave (Fraunhofer) Approximation



$$d = -x_1 \sin \theta$$
$$\sin \theta = \frac{x_0}{r_{01}} \approx \frac{x_0}{z}$$
$$d \approx -\frac{x_0 x_1}{z}$$

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Plane Wave Approximation

$$\frac{1}{r} \exp(jkr) \approx \frac{1}{z} \exp(jk(z+d)) = \frac{1}{z} \exp\left(j \frac{2\pi}{\lambda} \left(z - \frac{x_0 x_1}{z}\right)\right)$$
$$U(x_0) = \int_{-\infty}^{\infty} s(x_1) \frac{1}{r} \exp(jkr) dx_1$$
$$= \int_{-\infty}^{\infty} s(x_1) \frac{1}{z} \exp\left(j \frac{2\pi}{\lambda} \left(z - \frac{x_0 x_1}{z}\right)\right) dx_1$$
$$= \frac{1}{z} \exp\left(j \frac{2\pi}{\lambda}\right) \int_{-\infty}^{\infty} s(x_1) \exp\left(-j \frac{2\pi x_0 x_1}{\lambda z}\right) dx_1$$
$$= \frac{1}{z} \exp\left(j \frac{2\pi}{\lambda}\right) \int_{-\infty}^{\infty} s(x_1) \exp(-j 2\pi k_s x_1) dx_1$$
$$= \frac{1}{z} \exp\left(j \frac{2\pi}{\lambda}\right) F[s(x)]_{k_s, z \frac{x_0}{\lambda}}$$

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Plane Wave Approximation

In general

$$U(x_0, y_0) = \frac{1}{z} \exp\left(j \frac{2\pi z}{\lambda}\right) F[s(x, y)]_{k_x=\frac{x_0}{\lambda z}, k_y=\frac{y_0}{\lambda z}}$$

Example

$$s(x, y) = \text{rect}(x/D)\text{rect}(y/D)$$

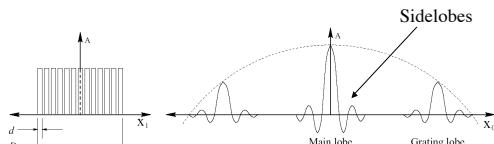
$$\begin{aligned} U(x_0, y_0) &= \frac{1}{z} \exp(jkz) D^2 \text{sinc}(Dk_x) \text{sinc}(Dk_y) \\ &= \frac{1}{z} \exp(jkz) D^2 \text{sinc}\left(D \frac{x_0}{\lambda z}\right) \text{sinc}\left(Dk_y \frac{y_0}{\lambda z}\right) \end{aligned}$$

$$\text{Zeros occur at } x_0 = \frac{n\lambda z}{D} \text{ and } y_0 = \frac{n\lambda z}{D}$$

$$\text{Beamwidth of the sinc function is } \frac{\lambda z}{D}$$

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Example



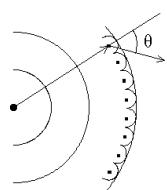
$$\text{rect}\left(\frac{x}{D}\right) \left[\text{rect}\left(\frac{x}{d}\right) * \frac{1}{d} \text{comb}\left(\frac{x}{d}\right) \right] \Leftrightarrow D \text{sinc}(Dk_x) * [d \text{sinc}(dk_x) \text{comb}(dk_x)]$$

Question: What should we do to reduce the sidelobes?

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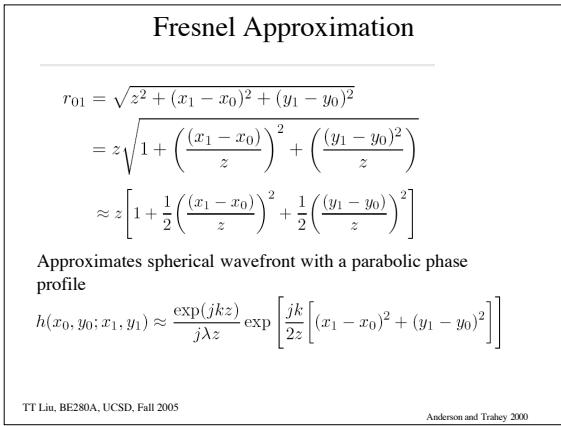
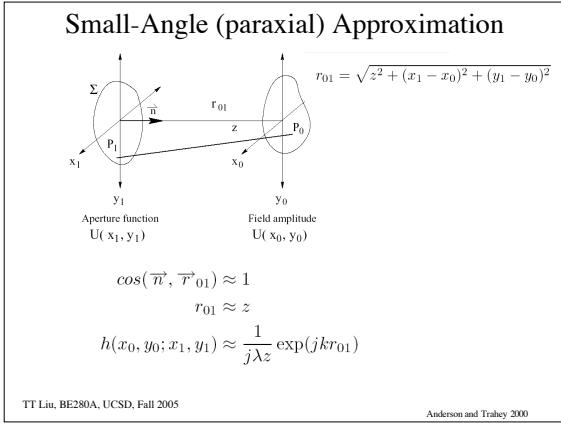
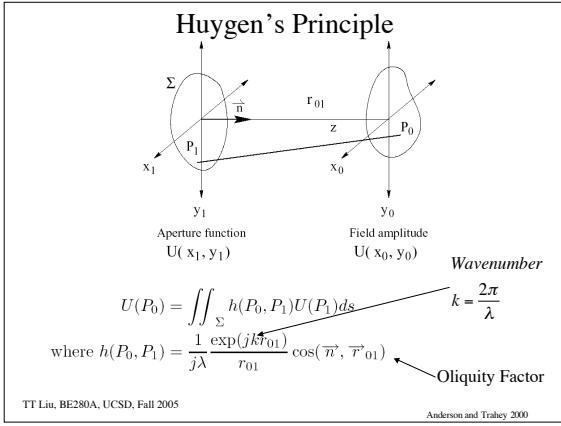
Huygen's Principle



<http://www.fink.com/thesis/chapter2.html>

<http://www.echem.imperial.ac.uk/urdan/diff/hfw.html>

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Fresnel Approximation

$$U(x_0, y_0) = \iint \frac{\exp(jkz)}{j\lambda z} \exp\left(\frac{jk}{2z}((x_i - x_0)^2 + (y_i - y_0)^2)\right) s(x_i, y_i) dx_i dy_i$$

$$= \frac{\exp(jkz)}{j\lambda z} \left(s(x_0, y_0) * * \exp\left(\frac{jk}{2z}(x_0^2 + y_0^2)\right) \right)$$

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Fraunhofer Approximation

$$kr_{01} \approx kz \left(1 + \frac{1}{2} \left(\frac{x_i - x_0}{z} \right)^2 + \frac{1}{2} \left(\frac{y_i - y_0}{z} \right)^2 \right)$$

$$= kz \left(1 + \frac{1}{2z^2} (x_i^2 - 2x_i x_0 + x_0^2) + \frac{1}{2z^2} (y_i^2 - 2y_i y_0 + y_0^2) \right)$$

$$= kz + \frac{k}{2z} (x_i^2 + y_i^2) + \frac{k}{2z} (x_0^2 + y_0^2) - \frac{k}{z} (x_i x_0 + y_i y_0)$$

$$\approx kz + \frac{k}{2z} (x_0^2 + y_0^2) - \frac{k}{z} (x_i x_0 + y_i y_0)$$

Assume this term
is negligible.

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Fraunhofer Condition

Phase term due to position on transducer is $\frac{k}{2z} (x_i^2 + y_i^2)$

Far-field condition is

$$\frac{k}{2z} (x_i^2 + y_i^2) \ll 1$$

$$z \gg \frac{k}{2} (x_i^2 + y_i^2) = \frac{\pi}{\lambda} (x_i^2 + y_i^2)$$

For a square DxD transducer, $x_i^2 + y_i^2 = D^2/4$

$$z \gg \frac{\pi D^2}{4\lambda} \approx \frac{D^2}{\lambda}$$

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Fraunhofer Approximation

$$U(x_0, y_0) \approx \frac{\exp(jkz) \exp\left[\frac{jk}{2z}(x_0^2 + y_0^2)\right]}{j\lambda z} \iint_{-\infty}^{\infty} U(x_1, y_1) \exp\left[-\frac{j2\pi}{\lambda z}(x_0 x_1 + y_0 y_1)\right] dx_1 dy_1$$

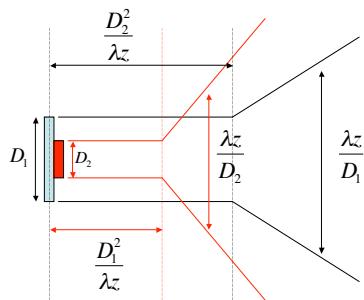
Quadratic phase term

Fourier transform of the source with

$$k_x = \frac{x_0}{\lambda z}, \quad k_y = \frac{y_0}{\lambda z}$$

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Transducer Dimension

Goal: Operate in the Fresnel Zone

$$z < D^2 / \lambda$$

$$D_{opt} \approx \sqrt{\lambda z_{max}}$$

Example

$$z_{max} = 20 \text{ cm}$$

$$\lambda = 0.5 \text{ mm}$$

$$D_{opt} = 1 \text{ cm}$$

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Focusing in Fresnel Zone

$$\begin{aligned}
U(x_0, y_0) &= \int \frac{\exp(jkx)}{jkz} \exp\left(\frac{jk}{2z}\left((x_1 - x_0)^2 + (y_1 - y_0)^2\right)\right) s(x_1, y_1) dx_1 dy_1 \\
&\quad - \int \frac{\exp(jkz)}{jkx} \exp\left(\frac{jk}{2z}\left((x_1^2 + y_1^2) + (x_0^2 + y_0^2) - 2(x_1 x_0 + y_1 y_0)\right)\right) s(x_1, y_1) dx_1 dy_1 \\
&\quad - \int \frac{\exp(jkx)}{jkz} \exp\left(\frac{jk}{2z}(x_0^2 + y_0^2)\right) \int \frac{\exp(jkz)}{jkx} \exp\left(\frac{jk}{2z}(x_1^2 + y_1^2)\right) \exp\left(-\frac{jk}{z}(x_1 x_0 + y_1 y_0)\right) s(x_1, y_1) dx_1 dy_1
\end{aligned}$$

Use time delays to compensate for this phase term

$$U(x_0, y_0) = \frac{\exp(jkz)}{j\lambda z} \exp\left(\frac{jk}{2z}(x_0^2 + y_0^2)\right) F\left[\exp\left(\frac{jk}{2z}(x_i^2 + y_i^2)\right) s(x_i, y_i)\right]$$

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Focusing in Fresnel Zone

$$U(x_0, y_0) = \frac{\exp(jkz)}{jkz} \exp\left(\frac{jk}{2z}(x_0^2 + y_0^2)\right) F\left[\exp\left(\frac{jk}{2z}(x_1^2 + y_1^2)\right) s(x_1, y_1)\right]$$

Make $s(x_1, y_1) = s_0(x_1, y_1) \exp\left(-\frac{jk}{2z_0}(x_1^2 + y_1^2)\right)$

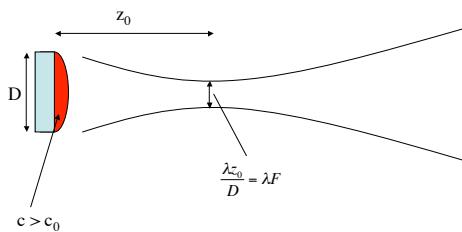
At the focal depth $z = z_0$

$$U(x_0, y_0) = \frac{\exp(jkz_0)}{j\lambda z_0} \exp\left(\frac{jk}{2z_0}(x_0^2 + y_0^2)\right) F[s(x_1, y_1)]$$

Beamwidth at the focal depth is: $\frac{\lambda z_0}{D}$

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Acoustic Lens



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Depth of Focus

When $z \neq z_0$, the phase term is $\Delta\Phi = \exp\left(-\frac{jk}{2z_0}(x_1^2 + y_1^2)\right) \exp\left(-\frac{jk}{2z}(x_1^2 + y_1^2)\right)$
and the lens is not perfectly focused.

Consider variation in the x - direction.

$$\Delta\Phi = \frac{kx^2}{2} \left(\frac{1}{z} - \frac{1}{z_0} \right)$$

For transducer of size D, $\frac{x^2}{2} = \frac{D^2}{4}$

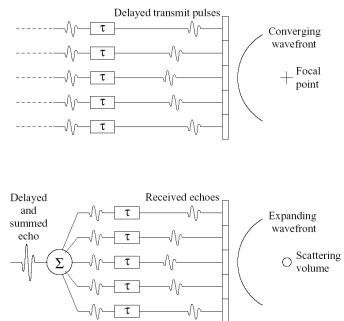
If we want $|\Delta\Phi| = \left| \frac{\pi D^2}{2\lambda} \left(\frac{1}{z} - \frac{1}{z_0} \right) \right| < 1$ radian then

$$\left| \frac{1}{z} - \frac{1}{z_0} \right| < \frac{2\lambda}{\pi D^2}$$

The larger the D, the smaller the depth of focus.

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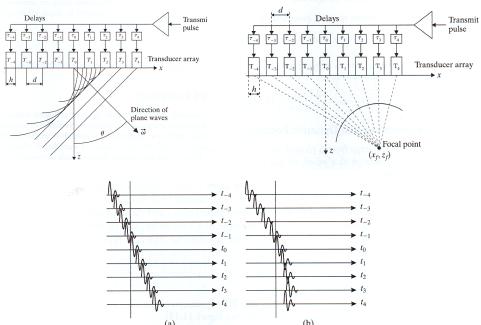
Focusing with Phased Array



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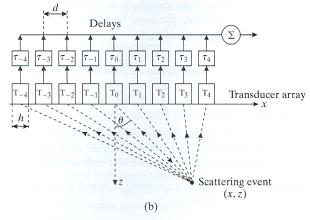
Focusing and Steering



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Dynamic Focusing



(b)

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