

Bioengineering 280A
Principles of Biomedical Imaging

Fall Quarter 2005
X-Rays/CT Lecture 1

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Topics

- X-Rays
- Computed Tomography
- Direct Inverse and Iterative Inverse
- Backprojection
- Projection Theorem
- Filtered Backprojection

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EM spectrum

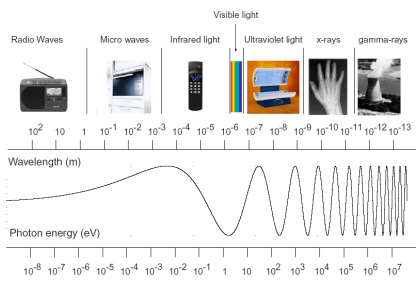
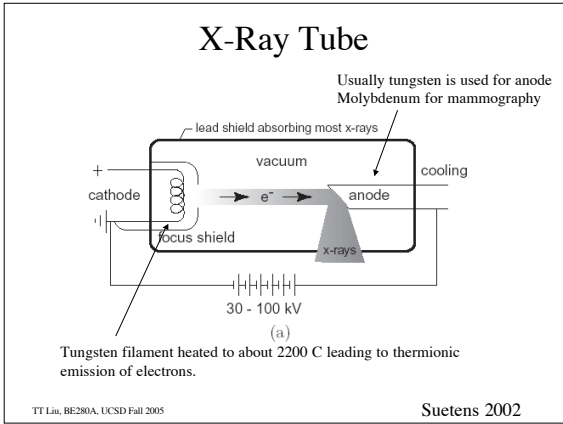
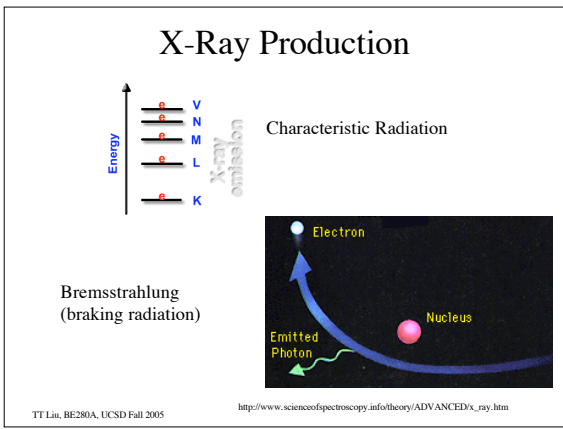


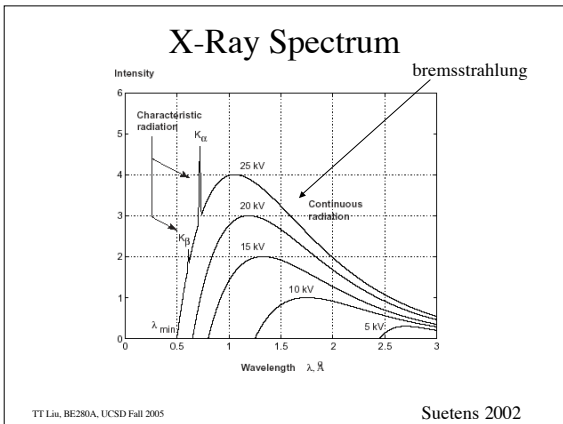
Figure 4.1: The electromagnetic spectrum.

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Suetens 2002







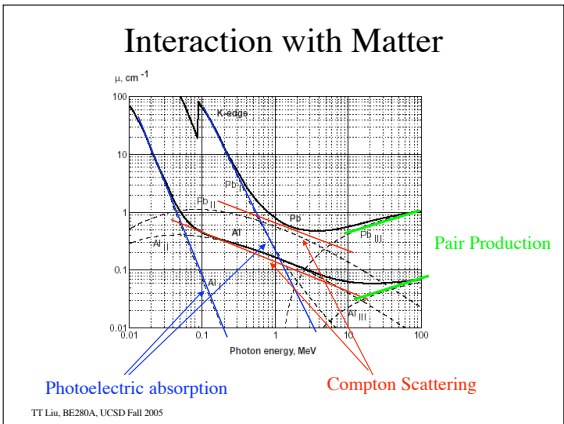
Interaction with Matter

Typical energy range for diagnostic x-rays is below 200 keV.
The two most important types of interaction are photoelectric absorption and Compton scattering.

Photoelectric effect dominates at low x-ray energies and high atomic numbers.

Compton scattering dominates at high x-ray energies and low atomic numbers, not much contrast.

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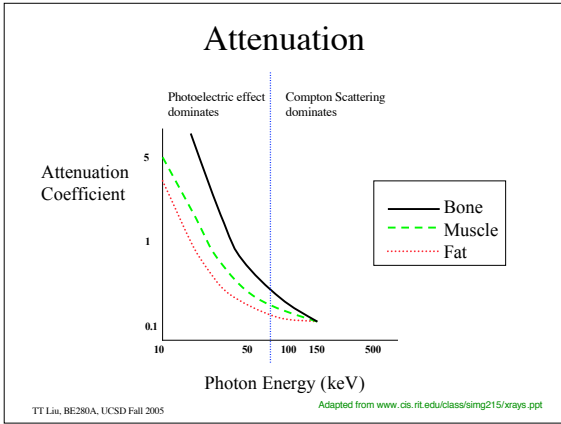
Attenuation

For single-energy x-rays passing through a homogenous object:

$$I_{out} = I_{in} \exp(-\mu d)$$

Linear attenuation coefficient

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Half Value Layer

X-ray energy (keV)	HVL, muscle (cm)	HVL Bone (cm)
30	1.8	0.4
50	3.0	1.2
100	3.9	2.3
150	4.5	2.8

In chest radiography, about 90% of x-rays are absorbed by body. Average energy from a tungsten source is 68 keV. However, many lower energy beams are absorbed by tissue, so average energy is higher. This is referred to as beam-hardening, and reduces the contrast.

Values from Webb 2003

Attenuation

For an inhomogenous object:

$$I_{out} = I_{in} \exp\left(-\int_{x_{in}}^{x_{out}} \mu(x) dx\right)$$

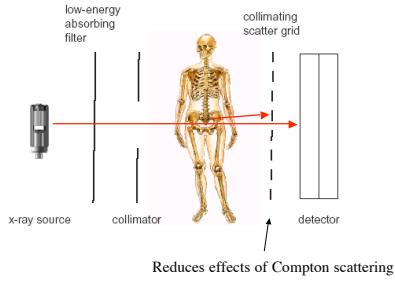
Integrating over energies

$$I_{out} = \int_0^\infty \sigma(E) \exp\left(-\int_{x_{in}}^{x_{out}} \mu(E, x) dx\right) dE$$

↙
Intensity distribution of beam

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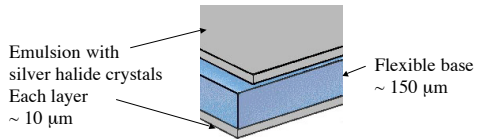
X-Ray Imaging Chain



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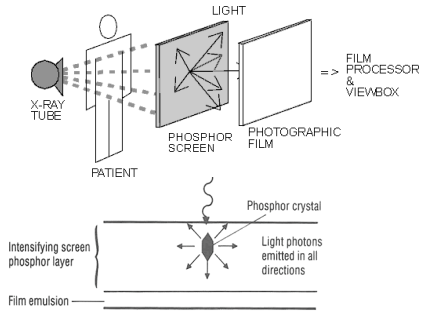
X-ray film



Silver halide crystals absorb optical energy. After development, crystals that have absorbed enough energy are converted to metallic silver and look dark on the screen. Thus, parts in the object that attenuate the x-rays will look brighter.

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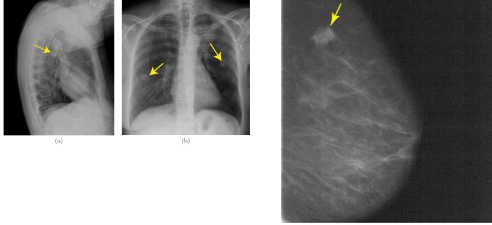
Intensifying Screen



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http://learntech.uwa.ac.uk/radiography/RS-science/imagina_principles_of_diagnostics11.htm
<http://www.sunnybrook.utoronto.ca/9080/~selenium/xray.html#Film>

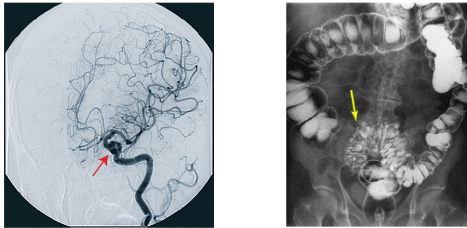
X-Ray Examples



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X-Ray w/ Contrast Agents



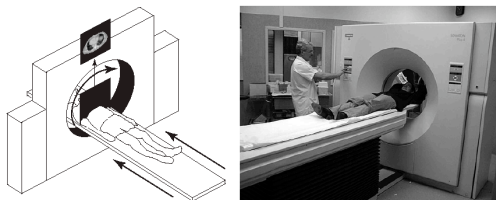
Angiogram using an iodine-based contrast agent.
K-edge of iodine is 33.2 keV

Barium Sulfate
K-edge of Barium is 37.4 keV

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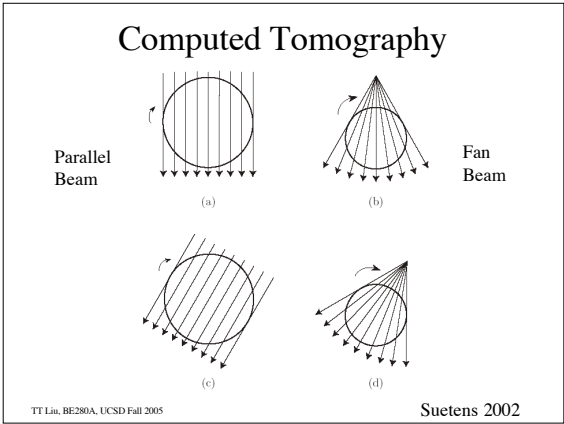
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Computed Tomography



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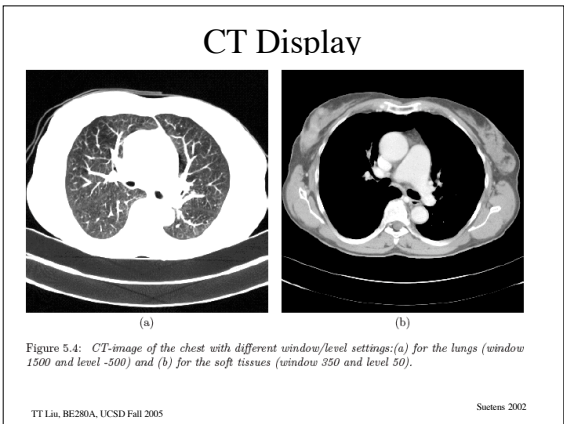
CT Number

$$CT_number = \frac{\mu - \mu_{water}}{\mu_{water}} \times 1000$$

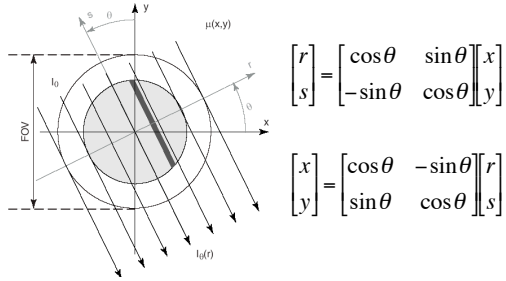
Measured in Hounsfield Units (HU)

Air: -1000 HU
 Soft Tissue: -100 to 60 HU
 Cortical Bones: 250 to 1000 HU

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Projections



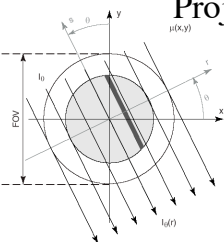
$$\begin{bmatrix} r \\ s \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} r \\ s \end{bmatrix}$$

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Projections



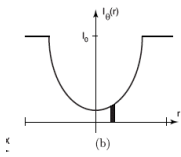
$$I_0(r) = I_0 \exp\left(-\int_{L_r, \theta} \mu(x, y) ds\right)$$

$$= I_0 \exp\left(-\int_{L_r, \theta} \mu(r \cos \theta - s \sin \theta, r \sin \theta + s \cos \theta) ds\right)$$

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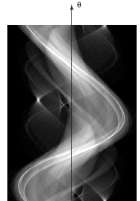
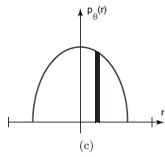
Projections



$$I_0(r) = I_0 \exp\left(-\int_{L_r, \theta} \mu(r \cos \theta - s \sin \theta, r \sin \theta + s \cos \theta) ds\right)$$

$$p_\theta(r) = -\ln \frac{I_0(r)}{I_0}$$

$$= \int_{L_r, \theta} \mu(r \cos \theta - s \sin \theta, r \sin \theta + s \cos \theta) ds$$

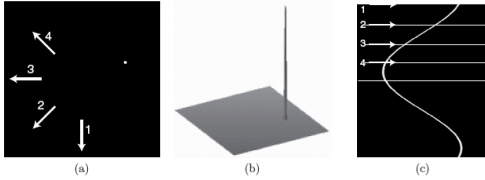


Sinogram

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Sinogram



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Systems 2002

Direct Inverse Approach

μ_1	μ_2
μ_3	μ_4

$$\begin{array}{l}
 p_1 \\
 p_2
 \end{array}
 \begin{array}{l}
 p_1 = \mu_1 + \mu_2 \\
 p_2 = \mu_3 + \mu_4 \\
 p_3 = \mu_1 + \mu_3 \\
 p_4 = \mu_2 + \mu_4
 \end{array}
 \begin{array}{l}
 \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu_1 \\ \mu_2 \\ \mu_3 \\ \mu_4 \end{bmatrix} \\
 \end{array}$$

4 equations, 4 unknowns.
Are these the correct equations to use?

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Direct Inverse Approach

μ_1	μ_2
μ_3	μ_4

$$\begin{array}{l}
 p_1 \\
 p_2 \\
 p_3 \\
 p_4 \\
 p_5
 \end{array}
 \begin{array}{l}
 p_1 = \mu_1 + \mu_2 \\
 p_2 = \mu_3 + \mu_4 \\
 p_3 = \mu_1 + \mu_3 \\
 p_4 = \mu_2 + \mu_4 \\
 p_5 = \mu_1 + \mu_4
 \end{array}
 \begin{array}{l}
 \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \\ p_5 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu_1 \\ \mu_2 \\ \mu_3 \\ \mu_4 \end{bmatrix} \\
 \end{array}$$

4 equations, 4 unknowns. These are linearly independent now.
In general for a $N \times N$ image, N^2 unknowns, N^2 equations.
This requires the inversion of a $N^2 \times N^2$ matrix
For a high-resolution 512×512 image, $N^2 = 262144$ equations.
Requires inversion of a 262144×262144 matrix!
Inversion process sensitive to measurement errors.

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**Iterative Inverse Approach
Algebraic Reconstruction Technique (ART)**

1	2	3	2.5	2.5	5
3	4	7	2.5	2.5	5
4	6	5			

→

1	2	3	1.5	1.5	3
3	4	7	3.5	3.5	7
5	5	5	5	5	

↓

1	2	3	2.5	2.5	5
3	4	7	2.5	2.5	5
4	6	5			

←

1	2	3	2.5	2.5	5
3	4	7	2.5	2.5	5
4	6	5			

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Backprojection

0	0	0	0
0	0	0	3
0	0	0	0
3	0	3	0

→

0	0	0	1
1	1	1	2
0	0	0	1

→

1	1	0	1
1	3	1	1
0	1	1	1

→

1	1	1	1
1	4	1	1
1	1	1	1

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Backprojection

$$b(x, y) = B\{p(r, \theta)\}$$

$$= \int_0^\pi p(x \cos \theta + y \sin \theta, \theta) d\theta$$

$$b(x_0, y) = p(r, \theta = 0) \Delta \theta$$

$$= p(x_0) \Delta \theta$$

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Backprojection

$$b(x, y) = B\{p(r, \theta)\}$$

$$= \int_0^\pi p(x \cos \theta + y \sin \theta, \theta) d\theta$$

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Backprojection

$$b(x, y) = B\{p(r, \theta)\} = \int_0^\pi p(x \cos \theta + y \sin \theta, \theta) d\theta$$

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Projection Theorem

$$U(k_x, 0) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} u(x, y) e^{-j2\pi(k_x x + k_y y)} dx dy$$

$$= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} u(x, y) dy \right] e^{-j2\pi k_x x} dx$$

$$= \int_{-\infty}^{\infty} p_0(x) e^{-j2\pi k_x x} dx$$

$$= \int_{-\infty}^{\infty} p_0(r) e^{-j2\pi k_x r} dr$$

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Projection Theorem

$$U(k_x, k_y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \mu(x, y) e^{-j2\pi(k_x x + k_y y)} dx dy$$

$$= F_{2D}[\mu(x, y)]$$

$$U(k_x, k_y) = P(k, \theta)$$

$$k_x = k \cos \theta$$

$$k_y = k \sin \theta$$

$$k = \sqrt{k_x^2 + k_y^2}$$

$$P(k, \theta) = \int_{-\infty}^{\infty} p_0(r) e^{-j2\pi k r} dr$$

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Fourier Reconstruction

Interpolate onto Cartesian grid
then take inverse transform

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Polar Version of Inverse FT

$$\mu(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U(k_x, k_y) e^{j2\pi(k_x x + k_y y)} dk_x dk_y$$

$$= \int_0^{2\pi} \int_0^{\infty} U(k, \theta) e^{j2\pi(k \cos \theta x + k \sin \theta y)} k dk d\theta$$

$$= \int_0^{2\pi} \int_{-\infty}^{\infty} U(k, \theta) e^{j2\pi(xk \cos \theta + yk \sin \theta)} |k| dk d\theta$$

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Filtered Backprojection

$$\begin{aligned} \mu(x, y) &= \int_0^\pi \int_{-\infty}^{\infty} U(k, \theta) e^{j2\pi(xk \cos\theta + yk \sin\theta)} |k| dk d\theta \\ &= \int_0^\pi \int_{-\infty}^{\infty} |k| U(k, \theta) e^{j2\pi k r} dk d\theta \\ &= \int_0^\pi u^*(r, \theta) d\theta \quad \leftarrow \text{Backproject a filtered projection} \end{aligned}$$

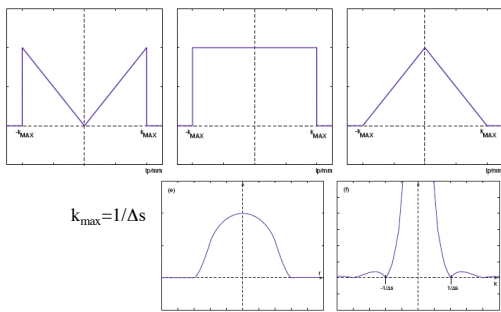
where $r = x \cos\theta + y \sin\theta$

$$\begin{aligned} u^*(r, \theta) &= \int_{-\infty}^{\infty} |k| U(k, \theta) e^{j2\pi k r} dk \\ &= u(r, \theta) * F^{-1}[|k|] \\ &= u(r, \theta) * q(r) \end{aligned}$$

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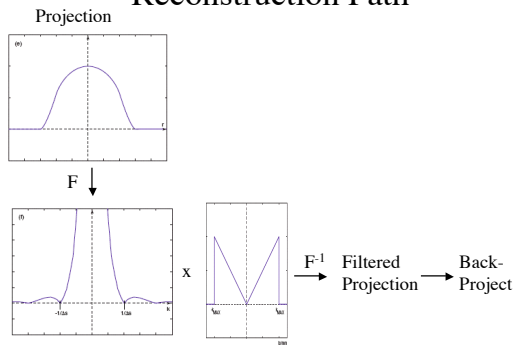
Ram-Lak Filter



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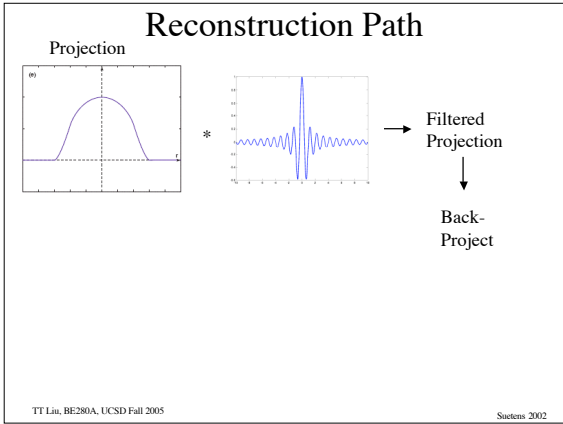
Saxena 2002

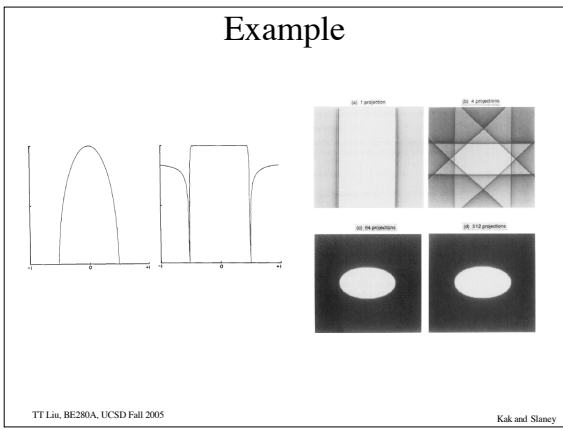
Reconstruction Path

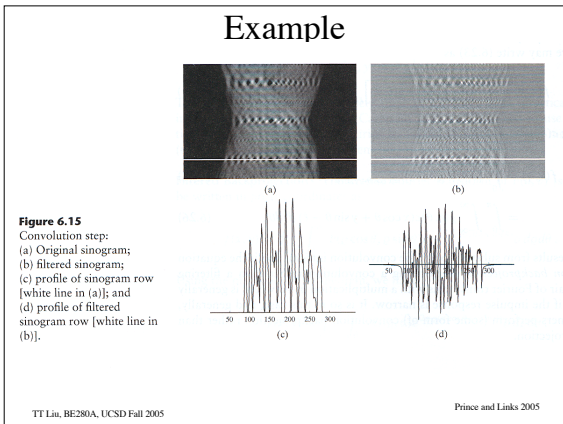


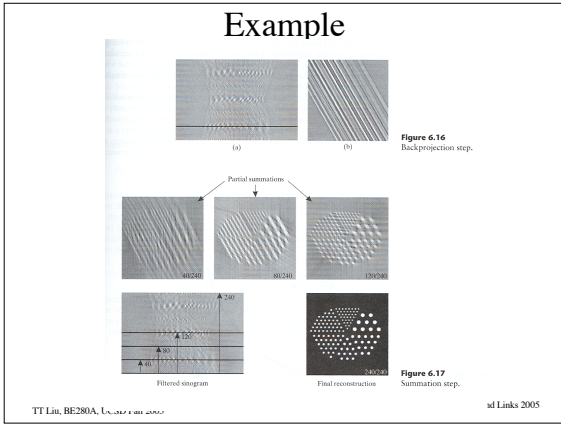
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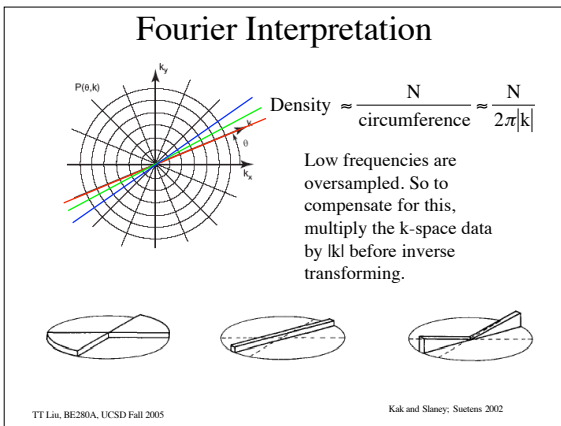
Saxena 2002

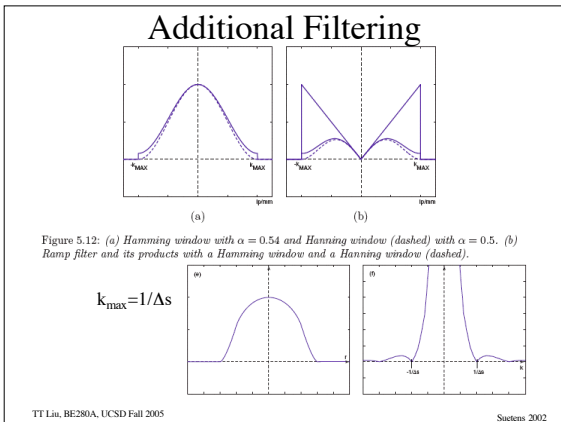


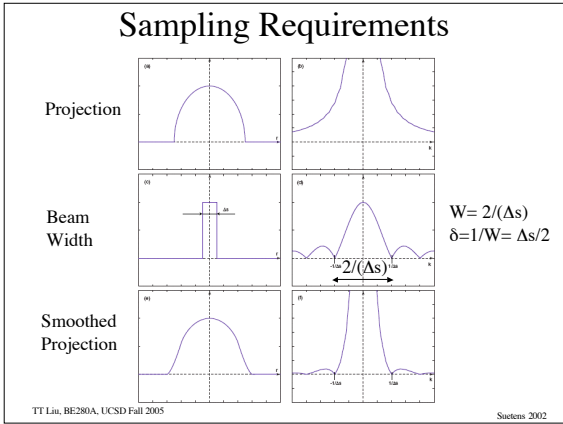


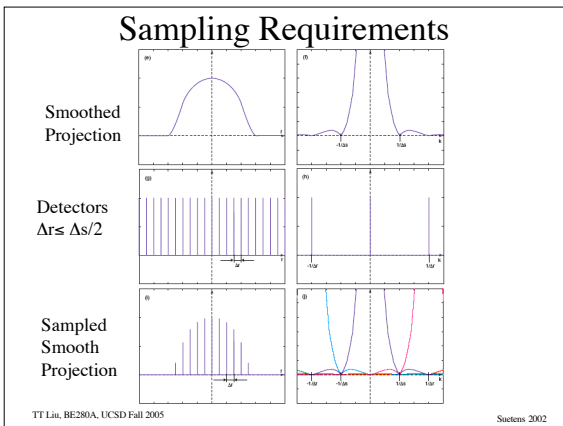












Sampling Requirements

Size of detector $\Delta r = \delta = 1/W = \Delta s/2$
 Number of Detectors $N = \text{FOV} / \Delta r$ where $\Delta r \leq \Delta s/2$
 Angular Sampling -- how many views?
 Want $\text{Circumference} / (\text{views in } 360 \text{ degrees}) = \Delta r$
 $\pi \text{FOV} / (\text{views}) = \Delta r = \text{FOV} / N$
 Number of views in 360 degrees = πN

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