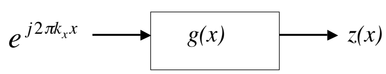
Bioengineering 280A
Principles of Biomedical Imaging

Fall Quarter 2007
CT/Fourier Lecture 3

Topics

- Modulation Transfer Function
- Convolution/Multiplication
- Modulation
- Revisit Projection-Slice Theorem
- Filtered Backprojection



$$
\begin{aligned}
z(x) &= g(x) * e^{j2\pi k_x x} \\
&= \int_{-\infty}^{\infty} g(u) e^{j2\pi k_x (x-u)} du \\
&= G(k_x) e^{j2\pi k_x x}
\end{aligned}
$$

The response of a linear shift invariant system to a complex exponential is simply the exponential multiplied by the FT of the system's impulse response.

Figure 1:

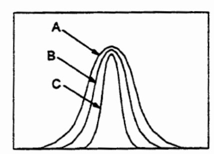
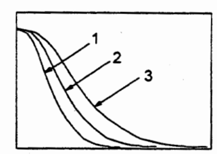


Figure 2:



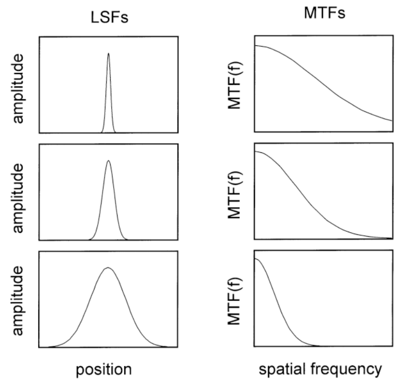
8. Referring to Figure 1 (above) which demonstrates 3 different line spread functions (LSF), which LSF will yield the best spatial resolution?

10. Referring to Figure 1 which shows LSFs, and Figure 2 which shows the corresponding modulation transfer functions (MTFs), which MTF corresponds to LSF C?

A. MTF number 1
B. MTF number 2
C. MTF number 3

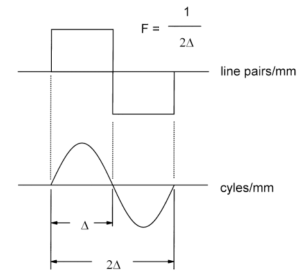
D74. The intrinsic resolution of a gamma camera is 5 mm. The collimator resolution is 10 mm. The overall system resolution is ______ mm.
A. 15
B. 11.2
C. 7.5
D. 5.0
E. 0.5

MTF = Fourier Transform of PSF

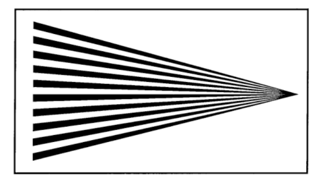


Bushberg et al 2001

Bushberg et al 2001

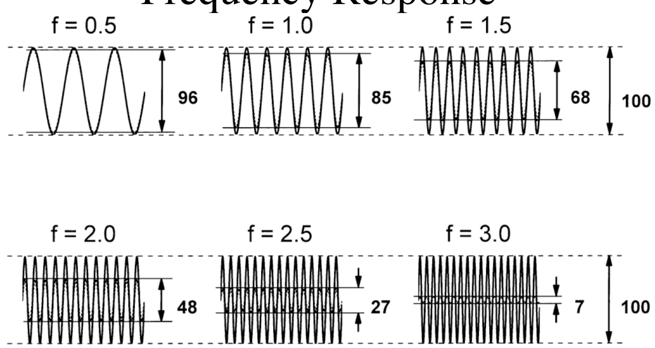


Line Pair Test Phantom



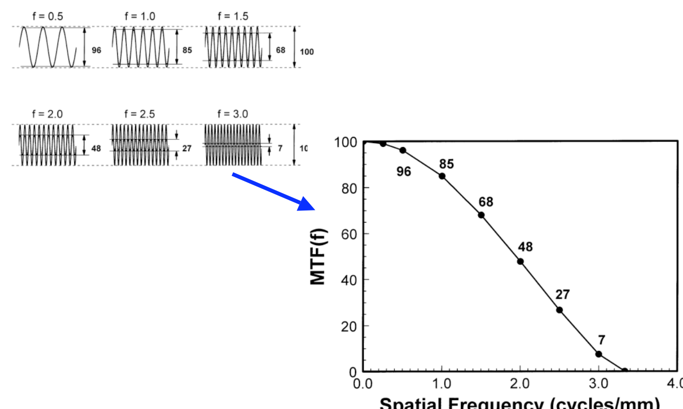
Section of a Star Pattern

Modulation Transfer Function (MTF) or Frequency Response



Bushberg et al 2001

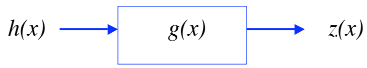
Modulation Transfer Function



Bushberg et al 2001

Convolution/Multiplication

Now consider an arbitrary input *h(x)*.



Recall that we can express *h(x)* as the integral of weighted complex exponentials.

$$h(x)=\int_{-\infty}^{\infty}H(k_x)e^{j2\pi k_x x}dk_x$$

Each of these exponentials is weighted by $G(k_x)$ so that the response may be written as

$$z(x)=\int_{-\infty}^{\infty}G(k_x)H(k_x)e^{j2\pi k_x x}dk_x$$

Convolution/Modulation Theorem

$$\begin{aligned}F\{g(x)*h(x)\}&=\int_{-\infty}^{\infty}\left[\int_{-\infty}^{\infty}g(u)*h(x-u)du\right]e^{-j2\pi k_x x}dx\\&=\int_{-\infty}^{\infty}g(u)\int_{-\infty}^{\infty}h(x-u)e^{-j2\pi k_x x}dxdu\\&=\int_{-\infty}^{\infty}g(u)H(k_x)e^{-j2\pi k_x u}du\\&=G(k_x)H(k_x)\end{aligned}$$

Convolution in the spatial domain transforms into multiplication in the frequency domain. Dual is modulation

$$F\{g(x)h(x)\}=G(k_x)*H(k_x)$$

2D Convolution/Multiplication

Convolution

$$F[g(x,y)**h(x,y)]=G(k_x,k_y)H(k_x,k_y)$$

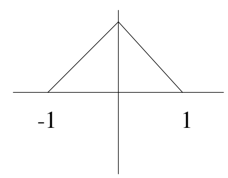
Multiplication

$$F[g(x,y)h(x,y)]=G(k_x,k_y)**H(k_x,k_y)$$

Application of Convolution Thm.

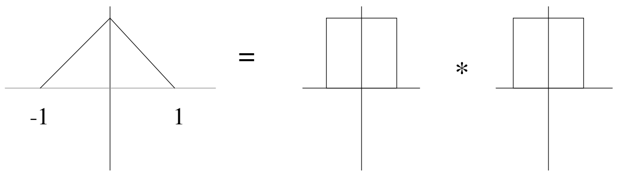
$$\Lambda(x)=\begin{cases}1-|x| & |x|<1\\ 0 & otherwise\end{cases}$$

$$F(\Lambda(x))=\int_{-1}^{1}(1-|x|)e^{-j2\pi k_x x}dx=??$$

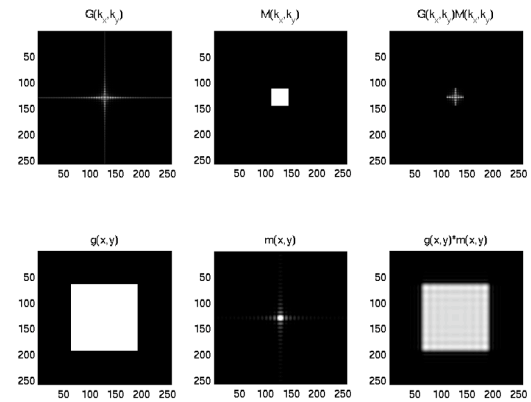


Application of Convolution Thm.

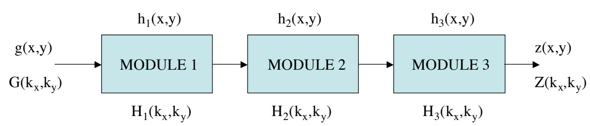
$$\Lambda(x) = \Pi(x) * \Pi(x)$$
$$F(\Lambda(x)) = \operatorname{sinc}^2(k_x)$$



Convolution Example



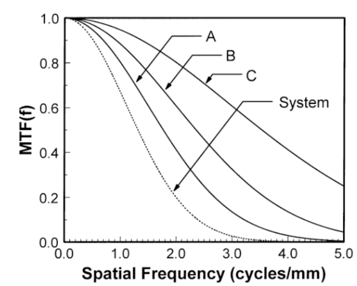
Response of an Imaging System



$z(x,y)=g(x,y)**h_1(x,y)**h_2(x,y)**h_3(x,y)$

$Z(k_x,k_y)=G(k_x,k_y)\ H_1(k_x,k_y)\ H_2(k_x,k_y)\ H_3(k_x,k_y)$

System MTF = Product of MTFs of Components



Bushberg et al 2001

Useful Approximation

$$FWHM_{System} = \sqrt{FWHM_1^2 + FWHM_2^2 + \cdots FWHM_N^2}$$

Example

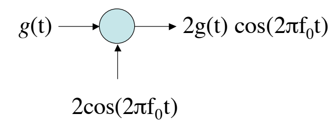
$$FWHM_1 = 1mm$$

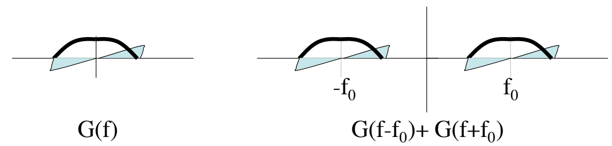
$$FWHM_2 = 2mm$$

$$FWHM_{system} = \sqrt{5} = 2.24mm$$

Modulation

Amplitude Modulation (e.g. AM Radio)





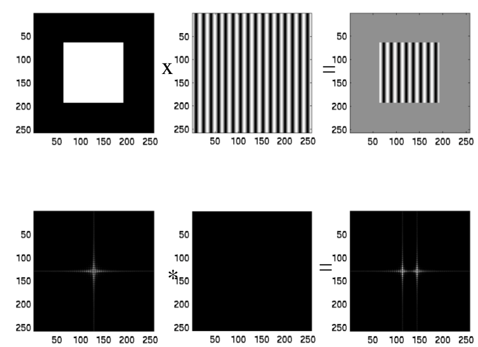
Modulation

$$F\left[g(x)e^{j2\pi k_0 x}\right] = G(k_x) * \delta(k_x - k_0) = G(k_x - k_0)$$

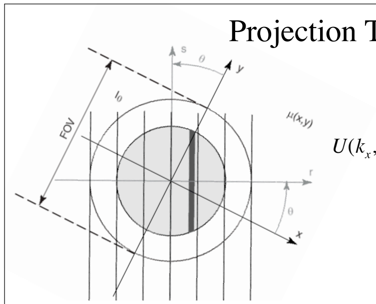
$$F\left[g(x)\cos(2\pi k_0 x)\right] = \frac{1}{2}G(k_x - k_0) + \frac{1}{2}G(k_x + k_0)$$

$$F\left[g(x)\sin(2\pi k_0 x)\right] = \frac{1}{2j}G(k_x - k_0) - \frac{1}{2j}G(k_x + k_0)$$

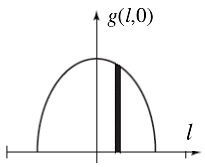
Modulation Example



Projection Theorem



$$U(k_x,0)=\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}\mu(x,y)e^{-j2\pi(k_x x+k_y y)}dxdy$$
$$=\int_{-\infty}^{-\infty}\left[\int_{-\infty}^{-\infty}\mu(x,y)dy\right]e^{-j2\pi k_x x}dx$$
$$=\int_{-\infty}^{-\infty}g(x,0)e^{-j2\pi k_x x}dx$$
$$=\int_{-\infty}^{-\infty}g(l,0)e^{-j2\pi kl}dl$$



In-Class Example:

$$\mu(x,y)=\cos 2\pi x$$

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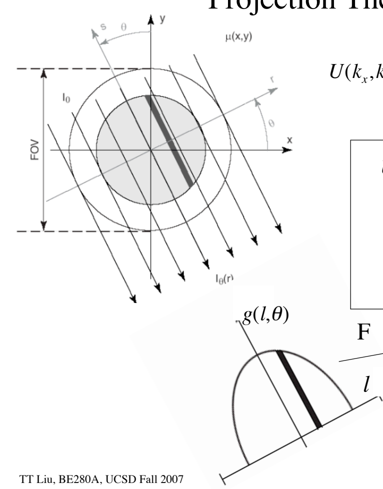
Suetens 2002

Projection Theorem



$$U(k_x,k_y)=\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}\mu(x,y)e^{-j2\pi(k_x x+k_y y)}dxdy$$
$$=F_{2D}\left[\mu(x,y)\right]$$

$$U(k_x,k_y)=G(k,\theta)$$
$$k_x=k\cos\theta$$
$$k_y=k\sin\theta$$
$$k=\sqrt{k_x^2+k_y^2}$$

$$G(k,\theta)=\int_{-\infty}^{\infty}g(l,\theta)e^{-j2\pi kl}dl$$

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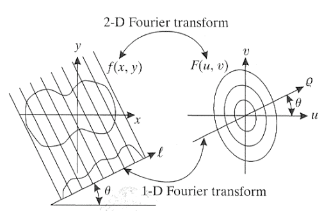
Projection Slice Theorem

$$G(\rho,\theta)=\int_{-\infty}^{\infty}g(l,\theta)e^{-j2\pi\rho l}dl$$
$$=\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}f(x,y)\delta(x\cos\theta+y\sin\theta-l)e^{-j2\pi\rho l}dx\,dy\,dl$$
$$=\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}f(x,y)e^{-j2\pi\rho(x\cos\theta+y\sin\theta)}dx\,dy$$
$$=F_{2D}\left[f(x,y)\right]\Big|_{u=\rho\cos\theta,v=\rho\sin\theta}$$



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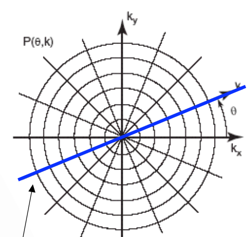
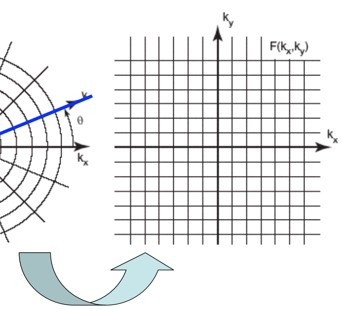
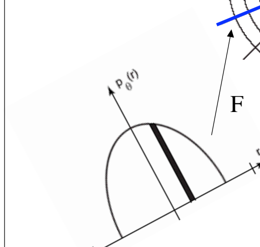
Prince&Links 2006

Fourier Reconstruction







F

Interpolate onto Cartesian grid then take inverse transform

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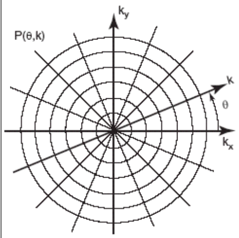
Polar Version of Inverse FT



$$\mu(x,y) = \int_{-\infty}^{\infty}\int_{-\infty}^{\infty} G(k_x,k_y) e^{j2\pi(k_x x + k_y y)} dk_x dk_y$$
$$= \int_0^{2\pi}\int_0^{\infty} G(k,\theta) e^{j2\pi(xk\cos\theta + yk\sin\theta)} k dk d\theta$$
$$= \int_0^{\pi}\int_{-\infty}^{\infty} G(k,\theta) e^{j2\pi k(x\cos\theta + y\sin\theta)} |k| dk d\theta$$

Note :

$g(l,\theta+\pi) = g(-l,\theta)$

So

$G(k,\theta+\pi) = G(-k,\theta)$

Suetens 2002

Filtered Backprojection

$$\mu(x,y) = \int_0^{\pi}\int_{-\infty}^{\infty} G(k,\theta) e^{j2\pi(xk\cos\theta + yk\sin\theta)} |k| dk d\theta$$
$$= \int_0^{\pi}\int_{-\infty}^{\infty} |k| G(k,\theta) e^{j2\pi kl} dk d\theta$$
$$= \int_0^{\pi} g^*(l,\theta) d\theta$$

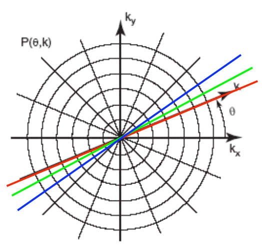
← Backproject a filtered projection

where $l = x\cos\theta + y\sin\theta$

$$g^*(l,\theta) = \int_{-\infty}^{\infty} |k| G(k,\theta) e^{j2\pi kl} dk$$
$$= g(l,\theta) * F^{-1}\left[|k|\right]$$
$$= g(l,\theta) * q(l)$$

Suetens 2002

Fourier Interpretation

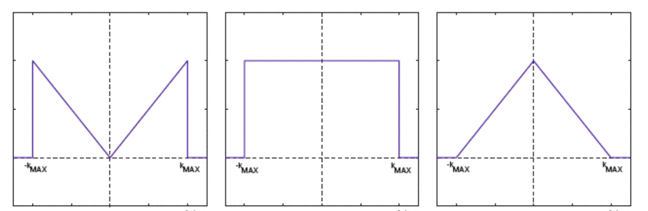


$$\text{Density} \approx \frac{\text{N}}{\text{circumference}} \approx \frac{\text{N}}{2\pi|\text{k}|}$$

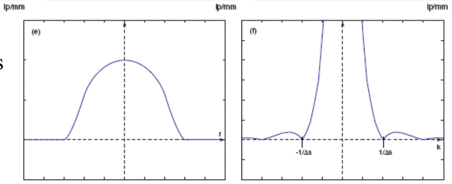
Low frequencies are oversampled. So to compensate for this, multiply the k-space data by |k| before inverse transforming.

Kak and Slaney; Suetens 2002

Ram-Lak Filter

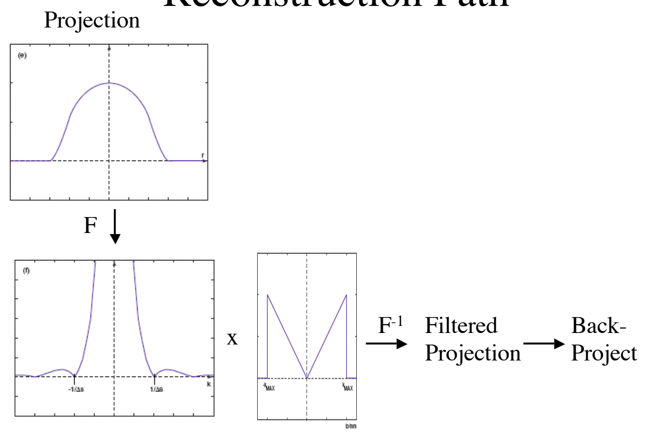


$k_{max}=1/\Delta s$



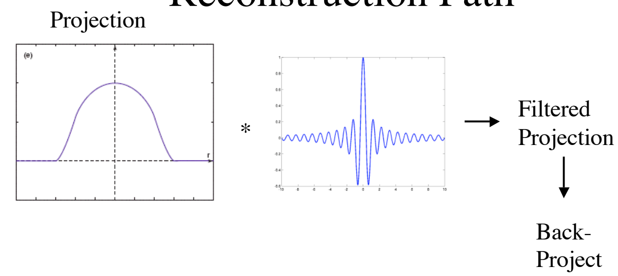
Suetens 2002

Reconstruction Path



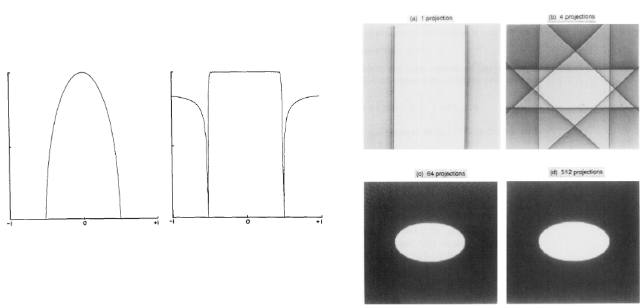
Suetens 2002

Reconstruction Path



Suetens 2002

Example



Kak and Slaney

Example

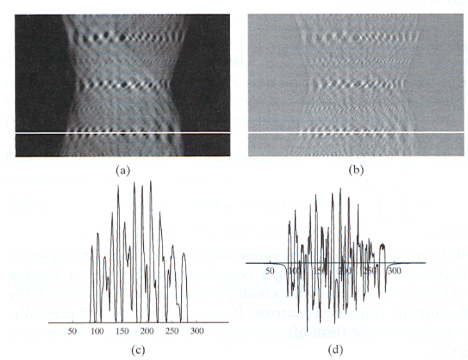


Figure 6.15
Convolution step:
(a) Original sinogram;
(b) filtered sinogram;
(c) profile of sinogram row [white line in (a)]; and
(d) profile of filtered sinogram row [white line in (b)].

Prince and Links 2005

Example

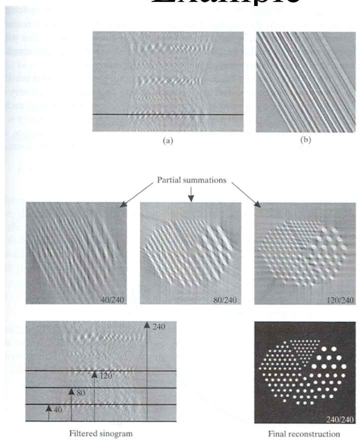


Figure 6.16
Backprojection step.

Figure 6.17
Summation step.

Prince and Links 2005